MA07-012 - COCOMINT: Cooperative Communications in Traffic Telematics

Zusammenfassung

Motivation. At current traffic levels, traffic telematics is an essential prerequisite for better traffic control and enhanced safety. Conventional cellular communication systems are not powerful enough for establishing real-time traffic information systems. New cooperative communication systems allow overcoming this bottleneck for traffic jams and high cruising speeds.

Research Goals. Relevant properties of vehicle-to-vehicle communication channels will be measured, analyzed, and modeled mathematically. Cooperative signaling schemes and respective receiver algorithms will be designed, implemented, and tested.

Socio-Economic Perspective. Traffic control systems based on cooperative communications have the potential to significantly improve traffic flow, and thus will minimize health hazards by reducing the number of accidents and harmful emissions.

Schlagworte:
wireless cooperative communications, analysis and optimizationof communication networks, traffic telematics, virtualMIMO systems, mobile sensor networks, distributed algebraicspace-time codes, random set theory, non-coherentcapacity

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Status: Abgeschlossen (01.02.2008 – 31.10.2010)

Weiterführende Links zu den beteiligten Personen und zum Projekt finden Sie unter
https://www.wwtf.at/funding/programmes/past/ma/MA07-012/